Research Article

Experimental Study of Natural Convective Heat Transfer from Vertical Rectangular Fin Array at Different Angle of Inclination

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Abstract

Steady state natural convective heat transfer from vertical rectangular fin array with isothermal and constant heat flux conditions is studied experimentally. Natural convective heat transfer from rectangular vertical fin array can be enhanced by optimizing the geometrical parameters such as fin length, width, height, and spacing. Also orientation of fin array, affects the natural convective heat transfer rate. An experimental set up was constructed to test 25 different fin arrays. Fin length and thickness were kept constant at L=200mm and t=2.5mm respectively. Fin spacing was varied from 5.5 to 14.5mm and height was varied from 5 to 25mm. Five different heat inputs ranging from 15W to 75W were supplied to all configurations. Experimentation revealed that optimization of geometrical parameters affects convective heat transfer rate. Effect of fin spacing on heat transfer rate was found more dominant than other geometrical parameters. It was observed that as fin spacing was increased, convective heat transfer rate also increases, reaches to maximum at a certain value of spacing known as optimum fin spacing and then decreases with further increase in spacing. Also it was observed that natural convective heat transfer rate is maximum for vertical orientation and it goes on decreasing as we incline fin array from vertical to horizontal.

Keywords: Natural convection, enhancement in heat transfer rate, geometrical parameters, angle of inclination, optimum fin spacing.

1. Introduction

In many engineering applications, during their operation heat is generated. If this generated heat is not dissipated rapidly to surrounding atmosphere, it may cause rise in temperature of the system components (Naidu, *et al*, 2010). This causes serious overheating problems in system and leads to system failure, so the generated heat within the system must be rejected to its surrounding for its efficient working (Burak, *et al*, 2007). Especially important in modern electronic systems, in which the packaging density of circuits can be high, engines, industrial equipment and a variety of mechanical devices, to overcome this problems fins as effective passive cooling device for thermal systems are suitable (Burak, 2005).

Simple and easiest way of rejection of heat from system to its surrounding is using fins andis used in various engineering applications successfully. The optimal combination of geometry and orientation of the finned surface are required to achieve the desired rate of heat dissipation (Tari, *et al*, 2013). Mostlyrectangular types of fins are used because of their low production cost, simple in construction, effectiveness, high cooling capability. It is possible to increase the heat transfer coefficient, h by forcing the air flow over the fins by using fans, but by using this option cost should be high and requires more space for to operate fans, therefore forced convection is not always preferable. Since the use of extended surfaces is often more economical, convenient and trouble free, most proposed application of increasing surface area is adding fins to the surface in order to achieve required rate of heat transfer(Burak, 2005). So, heat transfer by natural convection for dissipating unwanted heat from the fins is always better than forced convection. In order to increase the total heat transfer area, more fins added to the base. The number of the fins and fin optimum spacing should be calculated because it is observed that adding more fins to base, decreases the distance between the adjacent fins, because of this resistance to air flow and interference between boundary layers which affect in decrease the heat transfer coefficient (Tari et al, 2013).

2. Experimental Setup

2.1 Methodology

While performing experiments power input will be varying through dimmer stat. Power input is varied from 15 W to 75 W. After attaining steady state base

plate temperatures is measured. In order to decide whether the fin array is at steady state or not, the thermocouple readings are taken after half an hour interval and this condition can be assumed when difference between successive readings is less than 0.5° C. The base plate temperature T_w , the ambient temperature T_a and the power input P to heater is recorded at steady state. Testing procedure mentioned above is repeated for various heater inputs 15 W to 75 W.After all of the flow properties are known, Ra and Nu can be found as follows,

$$Ra = \frac{g \times \beta \times Lc^{3} \times (Tw - Ta)}{v \times \alpha} \qquad h = \frac{Qc}{As \times (Tw - Ta)}$$
$$Nu = \frac{h \times Lc}{K}$$

Where Lc is the characteristic length (length of the plate).

Theoretical Nusselt number can be calculated using following correlations :

1] McAdam's correlation

 $Nu = 0.59 \times Ra^{0.25}$

2] Churchill and Chu's first correlation

Nu =
$$\left[0.825 + \frac{0.387 \times Ra^{1/6}}{\left[1 + \left(\frac{0.492}{Pr}\right)^{9/16} \right]^{8/27}} \right]^2$$

3] Churchill and Chu's Second correlation $0.67 \times Ra^{1/4}$

$$Nu = 0.68 + \frac{1}{\left[1 + \left(\frac{0.492}{Pr}\right)^{9/16}\right]^{4/9}}$$

4] Churchill and Usagi's correlation $0.67 \times Ra^{1/4}$

$$Nu = \frac{0.67 \times Hu}{\left[1 + \left(\frac{0.492}{Pr}\right)^{9/16}\right]^{4/9}}$$

2.2 Experimental Equipment and Instrumentation



(a) Vertical Orientation (b) Inclined orientation Fig. 1 Experimental Set-up

- *2.3 Experimental setup consists of following components* 1. MS frame
- 2.Aerated concrete block
- 3. Heater plate
- 4. Thermocouples
- 5. Aluminum fins

- 6. Voltmeter
- 7. Ammeter
- 8. Dimmer stat
- 9. Multi point temperature indicator



Fig.2 Fin Models

Table 1 Dimension of setup

Component	Dimension (mm)		
Frame	1200*300*300		
Concrete	210*120*50		
Heater	200*75		

2.4 Comparison of Experimental Nusselt number with Theoretical Correlations

Four theoretical correlations considered to validate experimental value are :

1] Churchill and Chu's first correlation

Nu =
$$\left[0.825 + \frac{0.387 \times Ra^{1/6}}{\left[1 + \left(\frac{0.492}{Pr}\right)^{9/16}\right]^{8/27}}\right]^2 = 49.75779$$

2] Churchill and Chu's second correlation

Nu = 0.68 +
$$\frac{0.67 \times Ra^{1/4}}{\left[1 + \left(\frac{0.492}{P_T}\right)^{9/16}\right]^{4/9}} = 43.94409$$

3] Mac Adams correlation

Nu=0.59 x Ra^{1/4} = 49.7088

4] Churchill and Usagi's correlation $Nu = \frac{0.67 \times Ra^{1/4}}{\left[1 + \left(\frac{0.492}{Pr}\right)^{9/16}\right]^{4/9}} = 43.2609$ 5] Nu by experimentations = 40.78

Sample results of the analysis and the comparison of Nusselt number are given in Table 2.

Table 2 Comparison of Nusselt Number

Ra	Nu Expt.	Nu1	Nu2	Nu3
30370232.93	34.28	42.93	38.82	38.14
44365777.11	38.66	47.94	42.59	41.91
50387814.2	40.78	49.75	43.94	43.26

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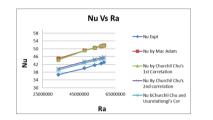


Fig.3 Comparison of Nusselt Number of Present Study with Theoretical Correlation

As shown in Table 2 and Fig. 3 Experimental Nusselt Number is compared with theoretical Nusselt number obtained from four theoretical correlations.

3. Scale Analysis

The main purpose of it is to obtain a relation for the optimum fin spacing that maximizes the heat transfer rate from vertical rectangular fins extending perpendicularly out of a vertical rectangular base. For the scale analysis, the procedure applied for rectangular fin array in Ref. (Burak, 2005) was adopted for the current geometry.

3.1 The Small-s Limit

In small-s limit, the boundary layer interferences occur immediately after air enters to the channels of the fin array, and therefore, the flow through each channel of the array can be assumed as fully developed channel flow. The total heat transfer rate from a single channel is given by(Burak, 2005):

$$\dot{Q}c_{\text{single channel}}^{(1)} = \dot{m}. C_p .\Delta T$$
 (3.1)

Where \dot{m} is the mass flow rate through a single channel, C_{p} is the specific heat of air at constant pressure and ΔT is order-of-magnitude of the temperature difference. From the scale analysis of continuity and momentum equations, mass flow rate can be written as:

$$\dot{m} \approx \frac{\rho * g * \beta * s^3 * \Delta T}{T}$$
. H (3.2)

If the number of channels (or the fins) is defined as n = W/s ($W/s \gg 1$), then the total heat transfer rate from the fins may be expressed as:

$$\dot{m} \approx \frac{\rho * g * \beta * s^3 * \Delta T}{\nu}$$
. H.C_p. $\Delta T. \frac{W}{s}$ (3.3)

Where $\dot{Q}_{c}^{(1)}$ is the difference between total convection heat transfer rate \dot{Q}_{c} , and the convection heat transfer from the base-plate, $(\dot{Q}_{o})_{c}$, as:

$$\dot{Q}_{c}^{(1)} = \dot{Q}_{c} \cdot (\dot{Q}_{o})_{c}$$
 (3.4)

In Eq. (3.4) \dot{Q}_{c} and $(\dot{Q}_{o})_{c}$ are evaluated at the same baseto-ambient temperature difference. Introducing the thermal diffusivity, α into Eq. (3.3), the following equation is obtained as:

$$\dot{Q}_{c1} \approx \frac{g * \beta * s^{3} * \Delta T}{\nu * \alpha}$$
. H.k.C_p. $\Delta T. \frac{W}{s}$ (3.5)
As seen from Eq. (3.5), in the small-s limit, the total

heat convection heat transfer rate is directly proportional with s^2 .

A dimensionless form of Eq. (3.5) may be obtained as : $\frac{\dot{Q}_c^{(1)}}{W} \approx \frac{g_*\beta_*s^3*\Delta T}{Q}$ (3.6)

$$\frac{1}{W} \frac{1}{W} \approx \frac{1}{V * \alpha}$$
(3.6)

The right hand side of Eq. (3.6) can be written in terms of Rayleigh number based on fin spacing as :

$$\frac{\dot{Q}_{c1}}{n \cdot H \cdot k \cdot \Delta T} \approx Ra_s$$
(3.7)

3.2 The Large-s Limit

In the large-s limit, the fin spacing, s is sufficiently greater than the boundary layer thickness, and hence, the boundary layers develop without any interference in the channel. Under boundary layer flow conditions, the total convection heat transfer rate from a single fin can be expressed as(Burak, 2005):

$$\dot{Q}c_{\text{single fin}}^{(2)} = 2 \cdot h. A \cdot \Delta T$$
 (3.8)

Where, h is the heat transfer coefficient over single fin, A is the area of single fin and ΔT is order-of-magnitude of the temperature difference.

Applying the scale analysis to Navier-Stokes equations and energy equation, heat transfer coefficient can be written as:

$$h \approx \left[\frac{\rho * g * \beta * L^3 * \Delta T}{\nu * \alpha}\right]^{0.25} \cdot \frac{k}{L}$$
(3.9)

If the area of the single fin, $A = H \cdot L$ and the number of fins, n = W/sare introduced into Eq. (3.9), the total heat transfer rate from the fins can be expressed as:

$$\dot{Q}_{c}^{(2)} \approx 2 \cdot \left[\frac{g * \beta * L^{3} * \Delta T}{\nu * \alpha} \right]^{0.25} \cdot \frac{k}{L} \cdot \text{H. L. } \Delta \text{T.} \frac{W}{s}$$
(3.10)

where $\dot{Q}_c^{(2)}$ is the difference between total convection heat transfer rate, \dot{Q}_c , and the convection heat transfer from the base-plate, ($\dot{Q}o$)c, as :

$$\dot{Q}_{c}^{(2)} = \dot{Q}_{c} - (\dot{Q}o)c$$
 (3.11)
Eq. (3.11) can be written in the following form as:

Eq. (3.11) can be written in the following form as: $\dot{O}_{2}^{(2)} \approx 2 \left[\frac{g^{*\beta * L^{3} * \Delta T}}{k} \right]^{0.25}$ k H AT $\frac{W}{2}$ (2.12)

$$2_c^{(3)} \approx 2 \cdot \left[\frac{\sigma - \sigma}{\nu * \alpha}\right] \quad \text{k. H. } \Delta T \cdot \frac{\sigma}{s}$$
(3.12)

As seen from Eq. (3.12), in the large-s limit, the convection heat transfer rate from the fins is inversely proportional with s..

A dimensionless form of Eq. (3.12) may be obtained as:

$$\frac{\dot{q}_{c}^{(2)}}{W} \approx 2 \cdot \left[\frac{g * \beta * L^{3} * \Delta T}{\nu * \alpha}\right]^{0.25} \mathbf{k} \cdot \mathbf{H} \cdot \Delta T \cdot \frac{W}{s}$$
(3.13)

The right hand side of Eq. (3.13) can be written in terms of Rayleigh number based on fin length as:

$$\frac{\dot{Q}_{c}^{(2)}}{n.\,k.\,H.\,\Delta T} \approx 2^{*}\,\text{Ra}^{0.25}$$
(3.14)

The trends of two curves reveal that the intersection of curves must give the maximum rate of total convection heat transfer which indicates the optimum fin spacing. As shown in Figure 4, the maximum occurs in the vicinity of the intersection (Burak, 2005):

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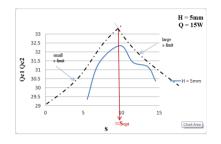


Fig. 4 Asymptotic Plot for Extreme Limits

Correlation obtained for optimum fin spacing is:

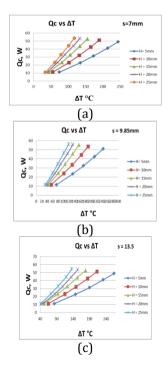
 $\frac{s_{opt}}{L}$ = 4.15 Ra^{-0.25}

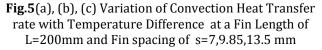
4. Results and Discussion

The experimental data obtained from 25 different fin configurations is considered. These all results are used to reveal the effect of said geometric parameters, orientation of finarray and heat input on the steady state heat dissipation from finned surfaces.

4.1 Effect of temperature difference over convective heat transfer rate for different heat input

The convection heat transfer rates from fin arrays are plotted as a function of temperature difference for fin lengths, L= 200 mm. Orientation of fin array is vertical i.e. $\theta = 0$. Heat Input is varied. Effect is verified for five different sets, i.e. for fin spacing of 5.5mm, 7mm, 9.85mm, 13.5mm and 14.5mm. In each set, fin height is varied as H=5 mm, 10mm, 15 mm, 20mm, 25 mm.





As observed in fig 5 (a) (b) and (c), nature of curve indicates that at a constant height and spacing convective heat transfer rate increases as temperature difference between base temperature and ambient temperature increases. At a given fin spacing, temperature difference between base temperature and ambient temperature decreases as fin height increases. Effect of fin spacing was observed to be more dominant than height on variation of convective heat transfer with respect to temperature difference.

4.2 Effect of angle of inclination over heat transfer rate for different fin height and heat input

The convection heat transfer rates from fin arrays are plotted as a function of angle of inclination for fin lengths, L= 200 mm and fin spacing, S=9.85 mm. Effect is verified for fin height H=5 mm, 15 mm, 25 mm. Angle of inclination is varied as $\theta = 0^{\circ}$, 30° , 45° , 60° , 90° . Heat Input is varied as 15W, 30W, 45W, 60W, 75W.

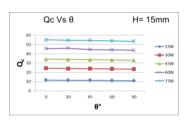
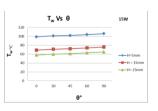


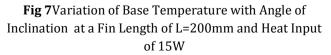
Fig.6Variation of Convection Heat Transfer rate with Heat Input at a Fin Length of L= 200mm and Fin Height H=15mm

As observed in fig 6, the convection heat transfer rate from fin arrays depends on inclination of heat sink. Convective heat transfer decreases from vertical position (0°) to horizontal position (90°).

4.3 Effect of angle of inclination over base temperature for different heat input and different fin height

As shown below effect of angle of inclination θ over base temperature T_w is observed for fin length of L= 200mm and fin spacing of s= 9.85mm. Angle of inclination is varied as θ = 0°, 30°, 45°, 60°, 90°. Effect was observed for Heat Input of 15W.





From fig.7, it was observed that value of base temperature increases as angle of inclination increases.

4.4 Effect of angle of inclination over heat transfer rate for different fin height

The effect of fin height on convection heat transfer rate at different angle of inclination was observed for heat input 45W. Fin spacing is s = 9.85 mm. Effect is verified for fin height H=5 mm, 10mm, 15 mm, 20mm, 25 mm. Angle of inclination is varied as $\theta = 0^{\circ}$, 30° , 45° , 60° , 90° .

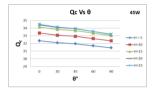
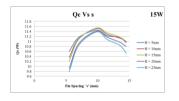


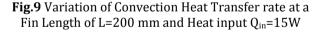
Fig.8 Variation of Convection Heat Transfer rate with angle of inclination at a Fin Length of L=200 mm and Heat input Q_{in} =45W.

As observed in fig.8, Convective heat transfer rate decreases as angle of inclination increases for a constant fin height.

4.5 Effect of fin spacing on convective heat transfer rate for different heat input

Effect of fin spacing on convective heat transfer rate is observed. Heat input is varied. At each heat input fin height is varied as 5mm, 10mm 15mm, 20mm, 25mm. At each fin height, fin spacing is varied as 5mm, 7.5mm, 9.85mm, 13.5mm, and 14.5 mm.





From fig.9, it was observed that convective heat transfer rate first increases with increase in spacing upto certain limit and then decreases with further increase in spacing, and reaches to maximum at a certain value of spacing i.e. at an optimum value of spacing.Convective heat transfer rate was maximum between spacing of 9 mm and 11mm.Hence it was found that optimum fin spacing lies between 9mm and 11mm.

4.6 Effect of fin spacing on convective heat transfer rate for different $\Delta T(T_w - T_a)$

Effect of fin spacing on convective heat transfer rate was observed Heat input was varied. At each value of fin heights i.e. 5mm, 15mm, 25mm heat input was varied. At varying heat input at each value of $\Delta T(T_w$ –

T_a), fin spacing was varied as 5mm, 7.5mm, 9.85mm, 13.5mm, 14.

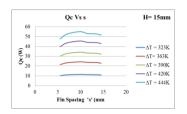


Fig.10 Variation of Convection Heat Transfer rate with spacing at a Fin Length of L=200 mm and Fin Height, H= 15mm

As observed from fig. 10, Convective heat transfer rate first increases with increase in spacing upto certain limit and then decreases with further increase in spacing, and reaches to maximum at a certain value of spacing i.e. at an optimum value of spacing. Itwas maximum between spacing of 9mm and 11mm.Hence it was found that optimum fin spacing lies between 9mm and 11mm.

Conclusions

(1) Natural convective heat transfer rate from vertical rectangular fin array is a function of geometrical parameters and angle of inclination. At a constant fin length, fin spacing and fin height affects the convective heat transfer rate most.

(2) It was found that natural convective heat transfer rate first increases with increase in spacing upto certain limit, reaches to maximum at a certain value of spacing i.e. at an optimum value of spacing and then decreases with further increase in spacing, and For present study value of optimum fin spacing was found between 9mm to 11mm.

(3) Experimental results obtained for optimum fin spacing were validated by scale analysis. Same results were obtained by scale analysis.

(4) Also it was observed that natural convective heat transfer rate is maximum for vertical orientation of fin array and it goes on decreasing as we incline fin array from vertical to horizontal. Therefore for better heat transfer vertical rectangular fin array is preferred than horizontal.

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